# MMA Memo 228: Analysis Of Tradeoffs In J-T Refrigerator Design

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# Abstract

This memo reports a theoretical study of some tradeoffs in the design of cryocoolers for temperatures of about 4K. In particular, it assumes a helium-4 Joule-Thompson (J-T) expander as the final refrigeration stage and considers the effect of the operating parameters of this stage on the total efficiency, including the necessary pre-cooling stage. The operating parameters are the temperature and pressure of the helium gas entering the J-T stage. Other design parameters are also considered, including the efficiencies of the heat exchangers, the efficiency of the pre-cooling refrigerator, and the efficiency of the J-T circuit compressor. It is found that the overall power consumption depends only weakly on the J-T supply pressure, but strongly on the pre-cooling temperature. High efficiency in the recuperative heat exchangers is essential (at least 98%). With perfect heat exchangers and with a precooler operating at 1% of Carnot efficiency, the optimum J-T inlet condition is P = 15 atm and T = 17 K. Only if the precooler is more efficient does it become worthwhile to pre-cool to significantly lower temperature. Under nearly all practical conditions, the total input power is dominated by that needed to run the precooler rather than that needed to compress the helium in the J-T circuit. With 99% efficient heat exchangers, pre-cooling at 3% of Carnot efficiency, and compression efficiency at 45% of adiabatic (all practical values), the total power required per unit cooling at 3.8K is 2800, of which 2125 is for pre-cooling to 12.5K and 675 is for compressing to 10 atm (i.e., for 0.5W at 3.8K, the predicted power consumption is 1400 W = 1062 W + 338 W). This is substantially better than is usually achieved, and is simply the result of careful optimization.

# Introduction

Helium Joule-Thompson cryocoolers have been in use for many years, including important applications in radio astronomy and space communication. Designs currently in use are largely based on early development work at CSIRO-Radiophysics [1], JPL [2-3], and the NRAO [4-5]. While the literature contains extensive discussions of the principles and descriptions of specific designs, the tradeoffs to be considered here do not seem to be covered elsewhere.

A J-T cryocooler consists of a source of high-pressure working fluid and a sink for low pressure working fluid, connected through an orifice. For some fluids in the proper initial state, adiabatic expansion across the orifice results in a drop in temperature and allows heat to be absorbed from a load. Ordinary room and vehicle air conditioners work in this way, with certain hydrocarbons or flouro-hydrocarbons as the working fluid. The efficiency can often be greatly increased by inserting a recuperative heat exchanger between the source/sink and the orifice.

Cooling during adiabatic expansion does not occur for ideal gases. Such cooling (the Joule-Thompson effect) depends on the compressed gas having some internal stored energy, typically caused by binding forces between molecules, into which kinetic energy (heat) can be transferred upon expansion. For each fluid, there may be a range of initial temperatures and pressures from which expansion results in cooling. For helium, the range is roughly temperatures of 10 to 40K at pressures of 10 to 30 atm. Lower initial temperature and higher initial pressure produce more cooling per unit mass. If the gas is supplied at room temperature, the J-T stage must be preceded by a substantial precooler in order to get the helium into the range where J-T cooling occurs. Various technologies may be used for the precooler, including multiple-stage J-T refrigerators using other fluids, but most commonly a reciprocating cryocooler such as a Gifford-McMahon refrigerator is used.

The expansion is considered adiabatic (without heat transfer) because an element of fluid takes very little time to cross the orifice. But very soon thereafter it may absorb heat from the load. The refrigeration temperature then depends on the pressure to which the fluid is expanded (return pressure) and on heat balance with the load. At sufficiently low pressure (<2.24 atm for He4) and sufficiently high flow rate to absorb heat from the load, the fluid may liquefy. Keeping liquid in contact with the load



Figure 1. Block diagram of J-T refrigerator, showing the notation used in the text.

then allows the refrigeration temperature to be determined only by the return pressure over a substantial range of loads. This has practical advantages when very stable temperature is required.

A block diagram of a typical J-T cryocooler for 4K is shown in Figure 1. It includes a compressor that supplies high pressure gas at room temperature and accepts low pressure gas at near room temperature. Two recuperative heat exchangers are used, one between room temperature and the precooler, and the second between the precooler and the J-T orifice. This allows the return gas to be warmed by the supply gas rather than by heat from the environment. In some practical systems the pre-cooling is done in two or more stages, separated by additional heat exchangers. But analysis shows that this has no beneficial effect; if the heat exchangers are efficient (>99%, as defined below), an intermediate pre-cooling stage near 70K absorbs almost no heat from the supply gas.

#### Analysis

Using the notation shown in Figure 1, we have a gas supply from the compressor at pressure  $P_s$ , which we take to be the same everywhere up to the J-T orifice (i.e., pressure drops in the pipes and heat exchangers are neglected [6]). Similarly, return pressure  $P_r$  is assumed to be constant from the J-T orifice back to the compressor. The temperature at the supply inlet of the first heat exchanger (HE1) is that of the environment, which if fixed here at  $T_0 = 300$ K. The temperature at the supply inlet of the second heat exchanger (HE2) is fixed by the precooler at  $T_1$ . Heat  $Q_2$  is absorbed from the load by each unit mass of helium. Given these independent variables, the temperature of the helium, and hence its thermodynamic state, will be calculated at all other points. This will determine the amount of work that must be done by the compressor as well as the amount of heat  $-Q_1$  that must be absorbed by the precooler; the latter implies an amount of work that the precooler must do to lift this heat to room temperature.

It is first necessary to consider the operation of counterflow heat exchangers such as we are using here. The objective of such a device is to transfer as much heat as possible from the warmer (inflowing) gas stream to the colder (outflowing) one. If the interaction length is made long enough, then this will be achieved. In that case, the temperatures of the gases on the warmer end of the heat exchanger will be equal. A finite length heat exchanger does not quite get the warm end temperatures equal, so not all of the possible heat transfer occurs. In addition, the heat exchanger may have thermal connections to sources other than the gases, for example by radiation or conduction. The net flow into the heat exchanger from such parasitic sources must be kept small by proper design. If there is a net flow out of the heat exchanger, then this helps to cool the incoming gas but it represents a load on some portion of the refrigeration system.

Referring to Figure 1 we can now define the thermal efficiency of a heat exchanger as

$$\eta = \frac{H(T_d, P_d) - H(T_c, P_c)}{H(T_a, P_d) - H(T_c, P_c) + Q_{\text{ext}}},$$
(1)

where H(T, P) is the enthalpy of the gas per unit mass as a function of temperature and pressure; the subscripts refer to the four ports of the device, alphabetically in the order of the gas flow; and  $Q_{\text{ext}}$  is

the net parasitic heat flow per unit mass. Here the denominator is the maximum possible heat transfer and the numerator is the actual heat transfer into the cold gas. Additionally, conservation of energy requires

$$H_d - H_c = H_a - H_b + Q_{\text{ext}} \tag{2}$$

where  $H_a = H(T_a, P_a)$ , etc. For convenience later, define  $H_x = H(T_a, P_d)$  as the enthalpy at port d for an ideal heat exchanger ( $\eta = 1$ ,  $Q_{\text{ext}} = 0$ ). An additional subscript 1 or 2 will refer to HE1 or HE2, respectively.

Using (1) and (2) we may now solve for any two thermodynamic variables, given all the others. In particular, it is easy to show that the heat absorbed from the load is

$$Q_2 = H_{c2} - H_{b2} = (H_{x2} + Q_{\text{ext}2})\eta_2 + H_{c2}(1 - \eta_2) - H_{a2}.$$
(3)

If we assume that the load operates under conditions where helium can be liquefied, then the gas at point c is in the saturated vapor phase and its state is determined by the return pressure  $P_r$  alone. If we now assume  $Q_{\text{ext2}} = 0$ , then the heat absorbed from the load  $Q_2$  is determined by  $P_s$ ,  $P_r$ ,  $T_1$ , and  $\eta_2$ .

The load on the precooler is just  $-Q_1 = H_{b1} - H_{a2}$ . Applying (1) and (2) to HE1 gives

$$H_{b1} = H_{a1} - (H_{x1} + Q_{\text{ext1}})\eta_1 + H_{c1}(1 - \eta_1).$$
(4)

Noting that  $H_{c1} = H_{d2}$  and applying (1) and (2) to HE2 gives

$$H_{c1} = H_{d2} = (H_{x2} + Q_{\text{ext}2})\eta_2 + H_{c2}(1 - \eta_2).$$
(5)

Finally, substituting yields

$$-Q_1 = H_{a1} - H_{a2} - H_{x1}\eta_1 + H_{x2}\eta_2\eta_1 + H_{c2}(1-\eta_2)\eta_1 + Q_{\text{ext1}}(1-\eta_1) + Q_{\text{ext2}}\eta_1\eta_2$$
(6)

for the precooler load. If we again neglect the parasitic heat flows, all quantities in (6) are determined by the same variables as determine  $Q_2$  plus the input gas temperature  $T_0 = 300$  K and the efficiency of the first heat exchanger  $\eta_1$ .

For a fixed value of refrigeration temperature  $T_2$  and therefore a fixed value of return pressure  $P_r$ , we would like to examine the total energy cost of a unit of load cooling  $Q_2$ , including both the cost of pumping the helium through the J-T circuit and that of precooling it. As shown above, these will depend only on the supply pressure  $P_s$ , the precooling temperature  $T_1$  and the heat exchanger efficiencies. Obviously, higher heat exchanger efficiencies are better. Generally, higher supply pressure results in more cooling per unit mass, but this requires more energy for compression; and lower precooling temperature also results in more cooling, but this requires more precooling energy. In view of the highly non-linear thermodynamic properties of helium in the temperature range of interest (4 to 30 K), the optimum tradeoff is not obvious.

**Compressors.** The compressor in Figure 1 must do work on the gas in order to raise its pressure from  $P_r$  to  $P_s$ . In practical rotary compressors operating at high angular speed (thousands of rpm), a particle of gas spends only ~ 100 msec being compressed. It is therefore a good approximation to assume adiabatic compression. The temperature of the gas particle is increased in this process, and it is then cooled by transferring heat to the environment in a separate heat exchanger. The work required to do the compression is easily determined from the properties of helium:

$$W_S = H(T_y, P_s) - H(T_0, P_r)$$

where  $W_S$  is the work done during adiabatic compression,  $T_0$  is the compressor input temperature (assumed equal to ambient), and  $T_y$  is the temperature such that  $S(T_y, P_s) = S(T_0, P_r)$  where S is the entropy per unit mass of the gas. Actually, the most efficient compressor is one that operates isothermally rather than adiabatically. To approximate this the compression must take place slowly and the compression chamber's walls must be have high conductivity to an ambient heat sink so as to allow



Figure 2. (a): Top. Total work per unit cooling at 3.8K, vs. precooling temperature and supply pressure, with ideal heat exchangers and with precooling efficiency typical of a small Gifford-McMahon refrigerator. (b): Bottom. Work per unit cooling for precooler and J-T compressor separately, at fixed supply pressure.

simultaneous cooling. Small, low speed reciprocating compressors may approach isothermal operation. In that case, the work required is

$$W_T = H(T_0, P_s) - H(T_0, P_r)$$

A practical compressor consumes additional energy because of friction, resistive loss in motors, the need to operate auxiliary machinery (e.g., fans and cooling circuit pumps), and similar effects. Nevertheless, large rotary compressors sometimes achieve efficiencies of more than 90% with respect to an ideal adiabatic compressor. Practical compressors in the size range usually used in radio astronomy have adiabatic efficiencies near 50% (see Table 1).

**Precooler Work.** Next, consider the work that must be done to achieve the precooling. We assume that the precooler rejects heat at ambient temperature  $T_0$ . If it were thermodynamically ideal

Mfgr/Model	$P_r$	$P_s$	$\dot{m}$	Power	$mW_S$	Adiabatic
	atm	atm	g/sec	W	W	Effic.
CTI/8200	7.8	18	1.45	2200	1048	48%
CTI/9600	7.8	18	3.74	5500	2712	49%
Hitachi/500RHH	6.7	18	4.42	6500	3757	58%

Table 1: Efficiencies of Some Commercial Compressors

Note: Power for Hitachi 500RHH is based on its use in Leybold model 4.2GM cryocooler system, where it operating near capacity; pressures and flow are from Hitachi data sheet. Data on other compressors supplied by CTI.

it would require the work input of the Carnot cycle, which is

$$W_c = Q_1 \frac{T_0 - T_1}{T_1}$$

In the temperature range of interest ( $T_1 = 10$  to 30K), practical cryocoolers achieve efficiencies of 1% to 30% of that of the Carnot cycle [8]. The highest efficiencies are achieved by large (kW range) Sterling-cycle machines; the cryocoolers commonly used in radio astronomy (Gifford-McMahon cycle coolers at a few watts capacity) have efficiencies around 2–3% of Carnot. Small Sterling coolers achieve about 10% of Carnot at 70K.

# Calculations

A spreadsheet was used to evaluate the above equations over a range of the parameters. Helium properties were taken from [7]. The results are presented in Figures 2–6, as discussed below. For these calculations, the following parameters were held fixed:

$T_0 = 300 \text{ K}$	ambient heat rejection temperature and compressor in/out temperature;
$T_2 = 3.8 \text{ K}$	load temperature;
$P_r = 0.65 \text{ atm}$	J-T return pressure (consistent with $T_2$ );
$\eta_c = 45\%$	J-T compressor adiabatic efficiency.

Figure 2 shows the input work per unit cooling if the heat exchangers are ideal ( $\eta_1 = \eta_2 = 1.00$ ), as a function of the pre-cooling state  $T_1, P_s$ . Here the precooler efficiency is taken as 1% of Carnot, which is typical of small G-M cryocoolers for this temperature range. The optimum occurs at about  $T_1 = 16$ K and  $P_s = 15$  atm. The work is shown separately for the precooler and the J-T compressor in Figure 2b, as a function of  $T_1$  at fixed  $P_s = 15$  atm. At lower  $T_1$ , the J-T work is reduced but at a high cost in precooler work. As  $P_s$  increases, the J-T cooling per unit mass generally increases, allowing lower mass flow and hence lower pre-cooling power; but above about 10 atm this is overcome by the inverse J-T effect, so that pre-cooling power must nevertheless increase slightly. At very high pressures (above about 20 atm), the inter-atomic attraction responsible for the J-T effect starts to be reversed (becoming a repulsion) and the J-T efficiency decreases, requiring higher flow for a given amount of cooling. But as Figure 2a shows, the pressure dependence is fairly weak.

Figures 3 and 4 show the effect of imperfect heat exchangers. In Figure 3 the final heat exchanger  $(T_1 \text{ to the J-T orifice})$  is degraded to 98%; and in Figure 4 the pre-cooling heat exchanger  $(T_2 \text{ to the J-T orifice})$  is degraded to 98%. At  $T_1 \leq 15$ K, a few percent loss in the final heat exchanger is not significant because the enthalpy change  $H_{a2} - H_{d2}$  is a small fraction of the heat of vaporization (heat absorbed from the load). At higher precooling temperatures, and especially at lower pressures, the enthalpy change is larger so that a few percent loss in the heat exchanger causes a large loss of efficiency; above about 20K and below about 10 atm, it becomes impossible to reach 3.8K when  $\eta_2 < 0.98$ .

When HE1 is degraded (Fig. 4), the J-T circuit efficiency is not affected, but the precoder work increases substantially at all temperatures and pressures. This is because the supply gas exiting HE1 is at a higher temperature, requiring more cooling to reach  $T_1$ . For example, at  $P_s = 15$  atm and  $T_1 = 15$ K, we get  $T_{b1} = 16.8$ K if  $\eta_1 = 1.0$ ; but we get  $T_{b1} = 20.6$ K if  $\eta_1 = 0.98$ , so that the drop across the precoder has increased from 1.8K to 5.6K. The overall power required is thus very sensitive to the efficiency of the first heat exchanger.



Figure 3. Like Fig. 2, but with HE2 efficiency reduced to 98%.

The above conclusions are dependent on the assumption that the precooler is rather inefficient (only 1% of Carnot), so that its power requirements dominate (Figs. 2b, 3b, 4b). The situation is somewhat different with a more efficient precooler, as shown in Figure 5. Here the heat exchangers are again perfect, but the precooler operates at 10% of Carnot. Since precooling is no longer so expensive, it becomes advantageous to operate at lower  $T_1$ , with the optimum around 10K. The optimum supply pressure is still 10 to 15 atm, with weak dependence.

Finally, it is instructive to consider the size of the load on the precooler. Figure 6 shows  $-Q_1/Q_2$  under selected conditions. Except in the inefficient regime  $T_1 > 15$ K, we see that the precooling load is 1.2 to 1.5 times the 3.8K capacity. A value of 1.5 is a good rule-of-thumb for design work.

#### **Practical Considerations**

As mentioned earlier, existing systems usually use more than one precooling stage. It is typical to have one additional stage at 50 to 80K. But whereas helium behaves nearly as an ideal gas in the range



Figure 4. Like Fig. 2, but with HE1 efficiency reduced to 98%.

300K to 50K, a set of perfect heat exchangers will cause the supply gas to be delivered to the additional precooler at its temperature, so that no heat is absorbed by there. In that case, we might as well have a single heat exchanger from ambient to  $T_1$ , as in the model of Figure 1. However, 300K to 15K is a large range for one heat exchanger. In practice, it might be difficult to achieve the required high efficiency  $(\eta_1 > 0.99)$  in a reasonably small device. The density of helium also changes by a factor of 20 over this range, so constructing the heat exchanger with tubes of constant cross section will cause them to be either too restrictive at the warm end or too large at the cold end. It therefore might be more practical to split HE1 into two parts, allowing the warmer part to be fairly inefficient (in order to keep it small) and including a precooler near 70K. The inefficiency will require the 70K precooler to absorb some heat, but since cooling at this temperature requires relatively low power the tradeoff might be reasonable. Available space and design effort can then be put into making the second part of the heat exchanger (70K to  $T_1$ ) very efficient, since this has the biggest effect on overall power consumption.



Figure 5. Like Fig. 2, but with a substantially more efficient precooler, typical of a small Sterling refrigerator.

The analysis also suggests some considerations for the J-T compressor. Although the optimum supply pressure is around 15 atm, degradation is slow as this pressure is reduced. Performance is essentially the same at 10 atm, and overall power is only 3% higher at 5 atm (Fig. 3b, at  $T_1 = 14$ K). By operating at 5–10 atm, the compression ratio is kept to 8–15 (for 3.8K with  $P_r = 0.65$  atm), allowing a single stage to be used. This greatly reduces cost and complexity compared with two-stage systems. In addition, consideration should be given to using a reciprocating compressor rather than a rotary one. By having one or more cylinders of high total displacement, a given flow rate can be achieved at low speed. The process then becomes closer to isothermal, with cooling during compression, which is considerably more efficient than adiabatic. Reciprocating compressors are generally considered to be less reliable than rotary ones because the former have more wear-limited moving parts; but the lower speed and lower operating temperatures may mitigate this when specific machines are compared.



Figure 6. Precooling power per unit cooling at 3.8K, vs.  $T_1$  and  $P_s$ , with ideal heat exchangers.

## References and Notes

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### Appendix A: Flow Systems and Enthalpy

[The following is an exposition of the concept of enthalpy and its usefulness in calculations of the sort considered in this memo. I include it here because I have been unable to find an equivalent explanation in a textbook.]

Consider the situation illustrated in Figure A1, where there is a continuous flow of fluid past boundary 1 into region X, and then out of region X past boundary 2. Let X be closed so that no fluid enters or exits via any other boundary. Inside X, the fluid may exchange work or heat or both or neither with the external environment. Since the flow is continuous, we consider the effect on a small element of fluid consisting of a fixed set of molecules.



Figure A1. Illustration of the notation used to explain the concepts of enthalpy and flow work.

The element is pushed past boundary 1 by the fluid that follows it, and it pushes on the fluid ahead of it when it passes boundary 2. Thus, the element does net work on the preceeding and following fluid in an amount

$$W_{\rm flow} = A_2 P_2 x_2 - A_1 P_1 x_1,$$

where  $A_i$  is the area of boundary *i*,  $P_i$  is the fluid pressure there, and  $x_i$  is the distance that the element must move to pass boundary *i*. Since  $A_i x_i = V_i$  is the volume of the element at boundary *i*, we also have

$$W_{\rm flow} = P_2 V_2 - P_1 V_1 = \delta(PV)$$

The first law of thermodynamics (conservation of energy) demands that the change of internal energy of the fluid element be given by

$$\delta U = Q - W$$

where  $W = W_{\text{flow}} + W_{\text{ext}}$ ,  $W_{\text{ext}}$  is the external work done by it while in region X, and Q is the heat flow into it while in region X. Substituting and rearranging gives

$$\delta(U + PV) = Q - W_{\text{ext}}.$$

Notice that the LHS of the last equation is the change in a quantity that is a function only of the fluid state at one point, and not of the way in which it got to that state. We can therefore define a state variable H = U + PV, called *enthalpy*. From this development it should be clear that enthalpy is useful in analyzing continuous-flow systems. The change in enthalpy per unit mass between any two points in the system gives the net external energy input per unit mass. If it is known that the intervening process is adiabatic (Q = 0), then the enthalpy change is the external work on the fluid (as in a compressor); and if it is known that the process involved no external work (as in a heat exchanger or orifice), then the enthalpy change is the external work (as in a heat exchanger or orifice), then the enthalpy change is the external heat absorbed. Enthalpy may be thought of as similar to the internal energy U, except that the effects of work done by the fluid on itself ("flow work" PV) have been taken into account.